KEVIN AUBERT

Phone: +1 (505)4178468 Email: kevin.aubertd@gmail.com

Website: http://tiny.cc/kevinaubert

Linkedin: https://www.linkedin.com/in/kevin-aubert-de-luchi-lomellini-a092021b6

I am a second-year Master's student in Electrical Engineering at the University of New Mexico, with a deep passion for motor racing, sports, and robotics. I have hands-on experience in high-profile competitions like Formula SAE and Shell Eco-Marathon, as well as advanced robotics projects involving UAVs as part of my research assistantship. I have strong technical expertise in Python, C++, MATLAB, Simulink, ROS2, and Autodesk Inventor, with a focus on systems control and autonomous robotics systems.

EDUCATION

University of New Mexico — New Mexico, USA MSc in Electrical Engineering: Second year	Aug. 2023 - Present GPA: 4.27 / 4.33	
Emphasis: Systems and Controls		
Relevant coursework: Machine Learning, Deep Learning, Autonomous N	Mobile Robots, Optimal Control.	
University of Engineering and Technology — Lima, Peru	2019 – Jul. 2023	
BS in Mechatronics Engineering	Rank: 1st place — GPA: 19.06 / 20.0	
Relevant coursework: Foundations of Robotics, Embedded Systems, Sensors and Actuators, Analysis of Signals and		
Systems, Control of Linear and Nonlinear Systems.		
A cademic Excellence Award recipient for 2020, 2021, and 2022		

Academic Excellence Award recipient for 2020, 2021, and 2022.

EXPERIENCE

MARHES: Multi-Agent, Robotics, and Heterogeneous Systems Laboratory	Feb. 2024 - Present
Research Assistant	New Mexico, USA

- · Support projects with AFRL on advanced robot manipulation and uncrewed aerial vehicle testbeds.
- Responsible for collecting data, preparing simulations, and developing hardware for various aerospace robotics projects at MARHES and AgMan (Agile Manufacturing) laboratories.
- · Develop and test drone-platforms to collect data from active volcanoes as part of UNM VolCAN Project.

Medicaltech Peru
Service Engineer

Aug. 2022 - Present *Lima*, Peru

- · Responsible for the maintenance and technical service of over 100 FotoFinder and Sinclair medical devices across Peru.
- Trained in Bulgaria in medical equipment technology for non-invasive procedures, covering pneumatic, hydraulic, and power electronics systems.

ENGINEERING PROJECTS

Formula SAE Lobo Motorsports

Electrical Department

· Led the restoration of the 2022 electric prototype, managing the integration of the battery, motor, and electrical systems.

KON Team - Shell Eco-Marathon

Chief Engineer

· Led the design, development, and optimization of our vehicle's systems to ensure top performance and efficiency.

- · Top 10 in Brazil 2023, Top 15 in Brazil 2022, and Top 25 in Americas 2023 in the electric battery prototype category.
- Ist world place in the Shell Eco-Marathon Virtual League 2022.

Mar. 2022 - Aug. 2023

Aug. 2023 - Dec. 2023

New Mexico, USA

Lima, Peru

TECHNICAL STRENGTHS

Programming Languages	Python, C++, R.
Engineering and Simulation Tools	MATLAB, Simulink, Fluidsim, ROS2, Gazebo, MuJoCo, Autodesk Inventor.
Office Software	MS Excel, MS PowerPoint, MS Word.
Languages	English (fluent), Spanish (native), German (basic)

PUBLICATIONS

[1] FlySurf: A Flying Robotic Surface with Shape Morphing Control American Control Conference (ACC) (under review)	2025
· Authors: Kevin Aubert, David Saldaña, and Rafael Fierro.	
[2] The Dynamic Duo: Sketch Boundary Mapping Executed by Drones International Conference on Robotics and Automation (ICRA) (under review)	2025
 Authors: John Ericksen, Kevin Aubert, Abir Islam, G. Matthew Fricke, Varsha Dani, Rafael Fierro Scott Nowicki, Jared Saia, and Melanie Moses. 	, Tobias Fischer,
[3] Decentralized Adaptive Aerospace Transportation of Unknown Loads Using A Team of R International Symposium on Distributed Autonomous Robotic Systems (DARS)	Robots 2024
· Authors: Longsen Gao, Kevin Aubert, David Saldaña, Claus Danielson, and Rafael Fierro.	
[4] Navigating the Edge: UAV Boundary Tracing for Efficient Volcanic Plume Monitoring International Symposium on Safety, Security, and Rescue Robotics (SSRR)	2024
 Authors: John Ericksen, Abir Islam, Carter Frost, Kevin Aubert, G. Matthew Fricke, Varsha Dar Tobias Fischer, Scott Nowicki, Jared Saia, and Melanie Moses. 	ii, Rafael Fierro,
[5] Land-Mobile Robots for Rescue and Search: A Technological and Systematic Review IEEE International IOT, Electronics and Mechatronics Conference (IEMTRONICS)	2022
 Authors: Deyby Huamanchahua, Kevin Aubert, Mirella Rivas, Eduardo Guerrero, Laura Kodaka, vara. Best Presenter Award 	and Diego Gue-
EXTRACURRICULAR AND VOLUNTARY EXPERIENCE	
University of Engineering and Technology Student Representative	2022 - 2023 Lima, Peru
\cdot Elected by the student community to act as a liaison between UTEC area heads and students for the 24	022-2023 period.
VID Organization Professor	2020 - 2021 Lima, Peru
• Taught scholars and pre-university students to raise funds for the Pérez Araníbar Childcare, an orphan	1age in Lima.
University of Engineering and Technology Academic Mentor	2020 - 2021 Lima, Peru
· Conducted classes in Physics, Statistics and Probability for first- and second-year students over three cons	secutive semester